

$$\mu(D) \geq \sqrt{\frac{n-m}{m(n-1)}}$$

$$m \leq n$$

For  $m < n$ , we get

$$\mu(D) \gtrsim \sqrt{\frac{m}{m(n-1)}} \approx \frac{1}{\sqrt{m}}$$

$$S < \frac{1}{2} \left( 1 + \frac{1}{\mu(D)} \right) \approx \frac{1}{2} \left( 1 + \sqrt{m} \right) \approx \frac{1}{2} \sqrt{m}$$

$$\begin{aligned} S &\sim \sqrt{m} \\ m &\sim S^2 \end{aligned}$$

square-root bottleneck

$\mathcal{DFT}$ -matrix, because of Vandermonde structure  $\Rightarrow m \geq 2s$

3 regimes: -  $m \geq 2s$  linear

-  $m \sim s \log n$  prob.

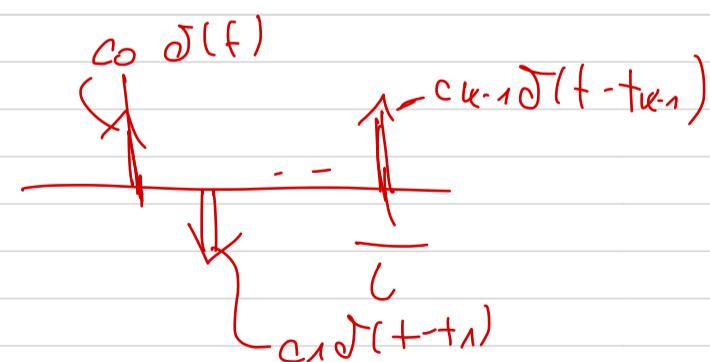
-  $m \sim s^2$  square-root bottleneck

#### 4. Finite Rate of Innovation

$$x(t) = \sum_{k=0}^{K-1} c_k \delta(t-t_k), t \in \mathbb{R}$$

$\delta(t)$  ... Dirac delta distribution

$$\int_{-\infty}^{\infty} \delta(t) e^{-i\omega t} dt = e^{-i\omega t_0} \Big|_{t=0} = 1$$



$$c_2 \delta(t-t_k) \xrightarrow{\mathcal{G}} c_2 e^{-i\bar{n}t_k f} = |c_2| e^{-i\bar{n}t_k f}$$

$$x = \sum x_k e^{ikf}$$

$$\varphi(\cdot) = -i2\pi t_k f \Rightarrow t_k = -\frac{\varphi(\cdot)}{2\pi i f}$$

Fourier series expansion of  $x(t)$ , assuming that  $x(t) = x(t + T)$

$$\begin{aligned} d_n &= \frac{1}{T} \int_0^T x(t) e^{-i\bar{n}t} dt \\ &= \frac{1}{T} \int_0^T \sum_{k=0}^{n-1} c_k \delta(t-t_k) e^{-i\bar{n}t} dt \\ &= \frac{1}{T} \sum_{k=0}^{n-1} c_k \int_0^T \delta(t-t_k) e^{-i\bar{n}t} dt \\ &= \frac{1}{T} \sum_{k=0}^{n-1} c_k e^{-i\bar{n}t_k}, \quad n \in \mathbb{Z} \end{aligned}$$

Berlekamp - Massey

Peterson - forensen - Zierler



"annihilating filter method"

starts with the convolution of a filter

$$A(z) = \sum_{m=0}^k a_m z^m$$

$$\tilde{x}(z) = \sum_n x_n z^{-n}$$



$$y_n =$$

$$\sum_{e=-\infty}^{\infty} x_e h_{n-e} = \sum_{e=-\infty}^{\infty} h_e x_{n-e}$$

convolution operation

$$(y(t) = x * h)(t) = \int x(\tau) h(t-\tau) d\tau$$

$$\hat{g}(f) = \hat{x}(f)\hat{h}(f)$$



$\mathcal{Z}$ -transform :  $a_n, n \in \mathbb{Z}$

$$A(z) = \sum_{n=-\infty}^{\infty} a_n z^{-n}$$

$$P(z) = \underbrace{(z-1)(z-2)}_{\text{product form}} = z^2 - 2z - z + 2 = \underbrace{z^2 - 3z + 2}_{A(z)}$$

$$A(z) = \frac{\kappa-1}{\|1\|} \left( 1 - e^{-i\tilde{\eta}_n \frac{t_n}{\tau}} z^{-1} \right)$$

$$Z(\sigma c_n) = \sum_{n=-\infty}^{\infty} \sigma c_n z^{-n}$$

$$\sum_{n=-\infty}^{\infty} x(n)z^{-n} = X(z)$$

$$\sum_{n=-\infty}^{\infty} x^{(n-1)} z^{-n} = \sum_{n'=-\infty}^{\infty} x^{(n')} z^{-(n'+1)} = z^{-1} x(z)$$

$$e^{-i\frac{\tau}{n} \frac{t_k}{T} n} * (\delta c_n - e^{-i\frac{\tau}{n} \frac{t_k}{T} i} \delta c_{n-1}) = e^{-i\frac{\tau}{n} \frac{t_k}{T} n} - e^{-i\frac{\tau}{n} \frac{t_k}{T} i} e^{-i\frac{\tau}{n} \frac{t_k}{T} (n-1)}$$

$$\delta[n] = \begin{cases} 1, & n=0 \\ 0, & n \neq 0 \end{cases} = e^{-i\bar{\omega}_n \frac{t_0}{T} n} - e^{\overbrace{-i\bar{\omega}_n \frac{t_0}{T}}^{\text{cancel}} n} e^{i\bar{\omega}_n \frac{t_0}{T} n}$$

$$d_n = \frac{1}{\tau} \sum_{k=0}^{N-1} c_k e^{-i \frac{\tau k}{\tau}} * \left( (\mathcal{J}c_n) - e^{-i \frac{\tau n}{\tau}} \mathcal{J}c_{n-1} \right) * \underline{\quad}$$

$$*(\underline{\quad}) = 0$$

$$d_n * a_n = 0$$

4.1. Finding the annihilating filter

$$d_n * a_n = \sum_{k=0}^K a_k d_{n-k} = 0$$

$$d_n = \frac{1}{c} \sum_{k=0}^{K-1} c_k u_k^n$$

$$S \in \mathbb{C}^{(K+1) \times (K+1)}$$

$$\begin{aligned} n=0 &\rightarrow \begin{bmatrix} d_0 & d_{-1} & \dots & d_{-K} \end{bmatrix} \\ n=1 &\rightarrow \begin{bmatrix} d_1 & d_0 & \dots & d_{-K+1} \end{bmatrix} \\ &\vdots \\ n=K &\rightarrow \begin{bmatrix} d_K & d_{K-1} & \dots & d_0 \end{bmatrix} \end{aligned}$$

$$\begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_K \end{bmatrix} = 0$$

Hankel matrix

$2K+1$  Fourier series coefficients

Finding the  $t_k$ 's &  $c_k$ 's

$$A(z) = \sum_{m=0}^K a_m z^{-m} = \prod_{i=0}^{K-1} \left( 1 - e^{-i \frac{\pi}{2} t_k} z^{-1} \right)$$

!!! To be resolved

Zeros of  $A(z)$  are given by

$$\begin{aligned} 1 - e^{-i \frac{\pi}{2} t_k} z^{-1} &= 0 \\ e^{i \frac{\pi}{2} t_k} - z^{-1} &= 0 \\ z_k &= e^{-i \frac{\pi}{2} t_k} \end{aligned}$$

$$t_k = -\frac{i}{2\pi} \arg(z_k)$$

#### 4.1.2. Finding the $c_k$ 's

$$d_n = \frac{1}{\tau} \sum_{k=0}^{K-1} c_k e^{-i \frac{\tau}{\tau} k n}$$

$U_k^n$ ,  $u_k = e^{-i \frac{\tau}{\tau} k}$

$$\frac{1}{\tau} \begin{bmatrix} 1 & 1 & - & 1 \\ u_0 & u_1 & - & u_{K-1} \\ u_0^2 & u_1^2 & - & \\ u_0^{K-1} & u_1^{K-1} & - & u_{K-1}^{K-1} \end{bmatrix}_{K \times K} \begin{bmatrix} c_0 \\ c_1 \\ \vdots \\ c_{K-1} \end{bmatrix}_{K \times 1} = \begin{bmatrix} d_0 \\ d_1 \\ \vdots \\ d_{K-1} \end{bmatrix}_{K \times 1}$$

Summary of the algorithm

given  $x(t) = \sum_{k=0}^{K-1} c_k J(t-t_k)$

1. Compute the Fourier series coefficients of  $x(t)$   
 $\Rightarrow d_n$

2. Out of the  $d_n$ , construct the matrix  $S$

3. find the right-singular vector corr. to the  
smallest ( $\Rightarrow$  iderly) singular value  
 $\Rightarrow a_n$

4. Find the zeros of the polynomial  $A(z) = \sum_{m=0}^K a_m z^m$

5. with these zeros, denoted as  $z_k$ , compute

$$\hat{t}_k = -\frac{\tau}{2\pi} \arg(z_k)$$

6. with these estimates for  $\hat{r}_k$ , i.e., with the  $\hat{r}_k^1$ ,  
construct  $\hat{\mathbf{F}}$  and solve for  $\mathbf{c}$

Dimension of null-space of  $\mathbf{S}$

$$\mathbf{S} = \frac{1}{c} \sum_{k=0}^{K-1} c_k \begin{bmatrix} 1 & u_k^{-1} & - & u_k^{-K} \\ u_k & 1 & & \\ u_k^2 & & & \\ \vdots & & & \\ u_k^K & & & \end{bmatrix}$$

$$= \frac{1}{c} \sum_{k=0}^{K-1} c_k \begin{bmatrix} 1 \\ u_k \\ u_k^2 \\ \vdots \\ u_k^K \end{bmatrix} \begin{bmatrix} 1 & u_k^{-1} & u_k^{-2} & \dots \end{bmatrix}$$

rank-1 matrix

$$\begin{bmatrix} 1 & 1 & - & \dots & 1 \\ u_0 & u_1 & & & u_{K-1} \\ u_0^2 & u_1^2 & & & u_{K-1}^2 \\ \vdots & \vdots & & & \vdots \\ 1 & 1 & & & 1 \end{bmatrix} \Rightarrow \text{full-rank}$$

$\Rightarrow$  uniqueness

Chapter 6 . The ESPRIT Algorithm

Pautraj, Roy, Kailath , 1986

$$x_n = \sum_{k=1}^K z_k z_k^n, \quad n \in \{0, 1, \dots, N-1\}$$

$$N \geq 2K$$

$$\text{cf. } d_n = \frac{1}{T} \sum_{k=0}^{N-1} c_k e^{-i \frac{2\pi}{T} k n}$$

$c_k$

$$z_k = e^{-d_k} e^{i 2\pi f_k}, \quad d_k > 0$$

$$|z_k| \leq 1$$

$$z_k^n = (e^{-d_k})^n e^{i 2\pi f_k n}$$

$$V_{L \times K} = \begin{pmatrix} 1 & 1 & \cdots & 1 \\ z_1 & z_2 & & z_K \\ z_1^2 & z_2^2 & & z_K^2 \\ \vdots & \vdots & \ddots & \vdots \\ z_1^{L-1} & z_2^{L-1} & & z_K^{L-1} \end{pmatrix}$$

L ≥ K

$$\mathcal{X}_L(x_0, x_1, \dots, x_{N-1}) = \begin{pmatrix} x_0 & x_1 & \cdots & x_{N-L-1} & x_{N-L} \\ x_1 & x_2 & \cdots & & x_{N-L+1} \\ x_2 & & \cdots & & \\ \vdots & & & & \\ x_{L-1} & & \cdots & & x_{N-1} \end{pmatrix}$$

$$1 \leq L \leq N$$

## 6.2. Signal & Noise Subspaces

$$X = \mathcal{H}_L(x_0, \dots, x_{N-1})$$

$$k+1 \leq L \leq N-k-1$$

$$X = V_L D_L V_{N-L+1}^T \in \mathbb{C}^{L \times (N-L+1)}$$

$$D_L = \begin{pmatrix} \alpha_1 & & & \\ & \alpha_2 & & \\ & & \ddots & \\ & & & \alpha_u \end{pmatrix}$$

$$\begin{pmatrix} 1 & z_1 & z_1^2 & \cdots & z_1^{N-1} \\ z_1 & z_2 & z_2^2 & \cdots & z_2^{N-1} \\ z_1^2 & z_2^2 & & & \\ \vdots & \vdots & & & \\ z_1^{L-1} & z_2^{L-1} & & & \end{pmatrix} = \begin{pmatrix} \alpha_1 & & & \\ & \alpha_2 & & \\ & & \ddots & \\ & & & \alpha_u \end{pmatrix}$$

$$= \begin{pmatrix} \alpha_1 & \alpha_2 & & & \\ \alpha_1 z_1 & \alpha_2 z_2 & & & \\ \alpha_1 z_1^2 & \alpha_2 z_2^2 & & & \\ & & \vdots & & \\ & & & \vdots & \\ & & & z_u & z_u^2 \end{pmatrix} - \begin{pmatrix} 1 & z_1 & z_1^2 & \cdots & z_1^{N-1} \\ 1 & z_2 & z_2^2 & \cdots & z_2^{N-1} \\ & & & | & \\ & & & & \\ & & & & \end{pmatrix}$$

$$= \begin{pmatrix} \sum_{q=1}^L \alpha_q & & & & \\ & \sum_{q=1}^L \alpha_q z_1 & & & \\ & & \vdots & & \\ & & & \vdots & \\ & & & z_u & z_u^2 \end{pmatrix} - \begin{pmatrix} 1 & z_1 & z_1^2 & \cdots & z_1^{N-1} \\ 1 & z_2 & z_2^2 & \cdots & z_2^{N-1} \\ & & & | & \\ & & & & \\ & & & & \end{pmatrix}$$

$$= \begin{pmatrix} \sum_{q=1}^L \alpha_q & \sum_{q=1}^L \alpha_q z_1 & & & \\ & \sum_{q=1}^L \alpha_q z_1 & \sum_{q=1}^L \alpha_q z_2 & & \\ & & \vdots & & \\ & & & \vdots & \\ & & & z_u & z_u^2 \end{pmatrix}$$

$$X = V_L D_L V_{N-L+1}^T \in \mathbb{C}^{L \times (N-L+1) \times u \times u \times (N-u+1)}$$

$$SVD(X) = \underbrace{\left( \begin{smallmatrix} L \times L \\ S_1 \\ \vdots \\ S_L \end{smallmatrix} \right)}_U \left( \begin{smallmatrix} L \times (N-L+1) & (N-L+1) \times (N-L+1) \\ \Delta & 0 \\ 0 & 0 \end{smallmatrix} \right) \underbrace{\left( \begin{smallmatrix} R^+ \\ R_{\perp}^+ \end{smallmatrix} \right)}_{W^H}$$

Sylvester's inequality

$$= S \Delta R^+$$

$$\text{rank}(A) + \text{rank}(B) - n \leq \text{rank}(AB) \leq \min \{\text{rank}(A), \text{rank}(B)\}$$

$\downarrow \quad \swarrow$   
m × n      n × s

$$k+k-n \leq \text{rank}(V_L D_L) \leq k \Rightarrow \text{rank}(V_L D_L) = k$$

$$k+1 \leq L \leq n-k-1$$

$$k \leq n-L-1$$

$$\text{rank}(X) = k$$

$$L \times (N-L+1)$$